

## **Department of Mechanical Engineering**

Phone: +1.903.566.7003 Fax: +1.903.566.7148 Uttyler.edu/engineering

## MENG 5396 – Thesis II Course Syllabus

	<del>-</del>
Semester / Year	Spring 2024
	Completion and defense of an accentable masteria thesis
Catalog	Completion and defense of an acceptable master's thesis.
Description	
Prerequisites	Advisor approval.
Section	004
Number	
Instructor	Dr. Chung-Hyun Goh
Name	
Contact	3900 University Blvd., RBN 3007, Tyler TX. 75799
Information	Phone: 903-566-6125
	Email: cgoh@uttyler.edu
Class Type /	Weekly meeting with the thesis advisor / RBN 3007
Instruction	
Mode /	
Location	
Class Time	TBA
Office Hours	M/Tu/W 10 am – 11 am or by appointment.
No. of Credits	3
Required	N/A
Textbook	
Optional	N/A
References	
Additional	N/A
Rules and	
Requirements	
Evaluation	Thesis committee approval
Method	**
Grading	CR (credit with semester credit hours awarded)
Policy / Scale	NC (no-credit with no semester credit hours awarded)
	IP (indicates In Progress; grade is changed only when coursework sequence is
	completed)
Important	Census date: 01/29/2024.
Events /	First drop for non-payment: 01/24/2024.
Dates	Last date to withdraw from one or more 15-week courses: 03/25/2024.
	Final report submission date: 04/25/2024.
Attendance /	Weekly meeting with the thesis advisor.
Makeup	
policy / other	
rules	



## Department of Mechanical Engineering Phone: +1.903.566.7003

Phone: +1.903.566.7003 Fax: +1.903.566.7148 Uttyler.edu/engineering

Course	By the end of this course, students will be able to:
Learning	1. Develop prototyping and validation & verification strategies in specific areas
Objectives /	assigned by the instructor.
ABET &	2. Produce simulation and/or experimental results for the specific thesis work.
PEOs	3. Interpret and analyze data obtained from the simulations and/or experiments leading
Relation	to a thesis work.
	4. Demonstrate the ability to write a thesis defense and present the findings to a thesis
	committee professionally.
Tentative	Integration of RoboREHAB (Robot-Assisted Rehabilitation Device).
Topics /	Prototyping and control design for leg assemblies in RoboREHAB.
<b>Course Plans</b>	Machine learning applications in Arduino.
	CAD design for daily activities using RoboREHAB.
	Technical manuscript writing.
University	https://www.uttyler.edu/academic-affairs/files/syllabus_information_2021.pdf
Policies	